

I-SMART: Implementing Small Manufacturer Assistance with Robotic Technologies



Are you Prepared?



WHAT IS I-SMART?

- A federally-funded program to support automation and robotics services for U.S. manufacturers.
- Provides manufacturers with access to MEP automation experts to:
 - *Identify automation opportunities*
 - *Develop the business case for specific applications*
 - *Connect manufacturers with additional automation resources*
 - *Assist with preparing for automation deployments*
 - *Consult on post-deployment optimization*
- Emphasis on helping manufacturers get “quick-wins” (fast payback)

What CAN I-SMART DO FOR ME?

- Start with a free automation implementation evaluation
 - *Remote or on-site visit by MEP/industry experts*
 - *Evaluate suitability of potential applications*
 - *Determine business case for best option(s):*
 - Cost/savings
 - Return on investment and payback period
 - *Provide written report to company on findings*
- Identify options for solution providers, assist with RFPs




WHAT CAN I-SMART DO FOR ME?

- Provide pre-deployment assistance
 - *Help plant leaders prepare workers for automation*
 - *Assist with redesign of process using Lean*
- Offer post-deployment support
 - *Replicate success of “quick-wins”*
 - *Generate additional business cases*
 - *Help optimize process*



WHAT CAN I-SMART DO FOR ME?

- Typical Process
 - Schedule date/time for site visit
 - Complete pre-visit questionnaire
 - Meet with key stakeholders
 - Tour shop floor and gather information on potential applications
 - Calculate financials
 - Provide written report on findings

Application Information Form			Date: 7/31/18	
Company: ██████████		Location: ██████████, IN		Contact: ██████████
Necessary Reach: Est URe 3 or 5		Line Identifier/Description: Deburr		Rating: (A) (B) (C) (X)
Shifts: Currently 8hrs per day/5 days a week. Bottleneck.		Part Size: 5 springs for high volume	Part Weight: grams	Throughput/Cycle: 150-200 per hr
Automation Driver(s): <ul style="list-style-type: none"> <input type="checkbox"/> Repetitive Motion Injury or other hazards <input type="checkbox"/> Ergonomics Improvement <input type="checkbox"/> Hiring difficulties <input type="checkbox"/> Retention/Turnover issues & training <input checked="" type="checkbox"/> Quality/Consistency issues <input checked="" type="checkbox"/> Labor costs <input type="checkbox"/> Other 		Considerations/Challenges: <ul style="list-style-type: none"> <input type="checkbox"/> Bin pick <input type="checkbox"/> Dexterity <input type="checkbox"/> Visual inspection <input checked="" type="checkbox"/> Precision/Tolerance <input type="checkbox"/> Low % able to automate w/Robot <input type="checkbox"/> Complex grippers <input type="checkbox"/> Environment <input type="checkbox"/> Reach <input checked="" type="checkbox"/> Push/Pull force <input type="checkbox"/> Changeover time <input checked="" type="checkbox"/> Ability to integrate 		Image/Notes: 
Notes: <ul style="list-style-type: none"> • Integration Note – <ul style="list-style-type: none"> ○ 8 total grinding stations ○ Likely 2-4 stations at new facility ○ Could isolate parts to always have at same deburr station ○ Cart / Array Tray system to be developed • Pick parts out of an array <ul style="list-style-type: none"> ○ If in well for picking – 1/8" each - in well / grip / above • Likely pick by OD in center of part <ul style="list-style-type: none"> ○ Gripping force could be several hundreds of newtons due to strength of spring • Part deburred on leading & back edge – OD & ID – 2 orbital rotations each • Force Torque Sensor (embedded in e-Series) to apply constant force • Track part counts to determine changing/maintenance of bit <ul style="list-style-type: none"> ○ Currently avg 1000 parts per bit change • TBD if parts go back in same pick position vs. into tumbler tote 				

QUESTIONS? WANT MORE INFORMATION?

Illinois



Tim Maurer
tmaurer@imec.org

Indiana



Kyle Squillace:
kbsquill@purdue.edu

Iowa



Shankar Srinivasan:
srigshan@iastate.edu